# VECTOR-S100 DC Variable Frequency Motor Roller Driver Three Braking Modes Acceleration And Deceleration Range 0.39~3.9s

## **Basic Information**

Place of Origin: China Jiangsu
 Brand Name: Winroller
 Certification: CE, SGS

Model Number: Winroller VECTOR-S100 DC Variable

Frequency Motor Roller Driver

Minimum Order Quantity: 1

Price: Contact Us
Packaging Details: Wooden case
Delivery Time: 7-15 word days
Payment Terms: L/C, T/T
Supply Ability: 1000000/year



## **Product Specification**

Product Name: VECTOR-S100 DC Variable Frequency

Motor Roller Driver

Rated Power Input: DC24V / 48V
 Allowable Voltage Range: 19~30V
 Rated Current: 4.2A
 Starting Current: 16.5A

Braking Mode: Electronic Brake, Free Brake, Servo Brake

• Color: White

 Acceleration And From 0.25 To 2S Deceleration:

• Highlight: Variable Frequency Motor Roller Driver,

DC24V Motor Roller Driver, DC24V roller drive motor



1.Signal terminal
2.Firmware upgrade port
3.Power terminal
4. DC+

8. DIP dialing 9. LED 10.ACC/DEC

6.Electric drum socket 7. SPEED

#### **Product Description**

# VECTOR-S100 DC Variable Frequency Motor Roller Driver Three Braking Modes Acceleration And Deceleration Range 0.39~3.9s

## Noun parsing of VECTOR-S100 DC Variable Frequency Motor Roller Driver

#### Brushless DC motor

The motor consists of a permanent magnet rotor and a stator wound with coils. This type of motor has the advantages of simple structure, high reliability, good stability, high efficiency, and strong adaptability, so it has been widely used.

#### Hall sensor

Since the brushless motor eliminates the carbon brush, the motor itself cannot run and needs to rely on an external driver to run. The Hall sensor is a device installed inside the motor to feedback position signals to the driver.

#### LEC

Light-emitting diodes are used to indicate the status of the drive system.

#### DNID/NIDN

The logic level of the effective control signal: NPN means low level is effective, that is, it is effective when connected to DC-; PNP means high level is effective, that is, it is effective when connected to DC+.

#### PLC

Industrial programmable logic controller.

#### Speed open/closed loop

Speed open loop, the drum speed decreases as the load increases;

Speed closed loop, when the load is within the rated torque of the drum, the drum speed does not change with the load.

#### **ECO and BOOST**

The electric C-type controller supports the electric roller ECO (energy saving) and BOOST (high torque) modes.

#### Vector frequency conversion

Field-oriented control is currently the best choice for efficiently controlling brushless DC motors.

#### Feature of VECTOR-S100 DC Variable Frequency Motor Roller Driver

- \*Three braking modes:Electronic brake, Free brake, Servo brake
- \*PNP and NPN adaptive: Give customers more options for control
- \*Acceleration and deceleration:Wide adjustment range, can achieve the time from 0.25 to 2S,16 accurate adjustment.
- \*3 speed gear:Convenient for customers to switch fast between acceleration and deceleration.
- \*Fail-safe restart: After the fault is rectified, the system automatically restarts within a certain period of time

# Comparison of VECTOR-S100 DC Variable Frequency Motor Roller Driver

# **Controller comparison**

		VECTOR-S100	VECTOR-K100	HB-100
Controlle	Comparative item		B ar account one	STATE OF THE PROPERTY OF THE P
Electrical specification	Rated power	DC24V/48V	DC20V~65V	DC19V-60V
Speed parameter	Speed adjustable range/rpm	600 ~ 6900	1000~6900	600~6900
	Acceleration and deceleration range/s	0.39 ~ 3.9	0.3~4	0.3-4
	Number of driving rollers	1	2	4
Electrical connection mode	PNP	√ (internal jumper)	✓ (Customer free choice)	√ (Customer free choice)
mode	NPN	✓ (internal jumper)	✓ (Customer free choice)	√ (Customer free choice)
Open-closed	Open loop	~	×	×
loop	Colsed loop	~	✓ (Default closed loop)	√ (Default closed loop)
	External analog	√ (0-10V)	×	
2	10	<b>√</b>	~	Profinet Ethernet
Control mode	Multi-speed	3 speed	7speed	CC-Link Modbus TCP
	RS485	V	· ·	
	Electronic Brake	<b>√</b>	×	~
Brake mode	Free brake	~	~	~
	Servo brake	<b>√</b>	~	~
Fault output	ERROR-N	×	wrong 0V, true +24V/48V	
	ERROR-P	×	wrong +24V/48V, true 0V	
	ERROR	PNP connection, true 13V, wrong 2V NPN connection, true 13V, wrong 2V	×	Computer control self-adaption

# Layout of VECTOR-S100 DC Variable Frequency Motor Roller Driver **Driver card layout**



- 1.Signal terminal
- 2.Firmware upgrade port
- 3.Power terminal
- 4. DC+
- 5. DC-
- 6.Electric drum socket
- 7. SPEED
- 8. DIP dialing
- 9. LED
- 10.ACC/DEC

### Layout of VECTOR-S100 DC Variable Frequency Motor Roller Driver

	or o
Power terminal	DC power input
	Control signal input and error signal output, some functions are used in conjunction with DIP dialing
DIP dialing	Function dialing
LED	Power and status lights
Electric drum socket	Special electric roller nine-pin square head socket
Firmware upgrade port	Firmware upgrade socket
SPEED	Speed selection
ACC/DEC	Acceleration/deceleration time setting

# **Driver Card External Interface**







Press down



0~10V analog speed regulation	External 0~10V analog voltage input speed adjustment
SPEED	Speed pulse feedback; PNP and NPN optional (controller internal jumper)
ERROR	Error signal output; PNP and NPN optional (controller internal jumper)
REVERSE	The drum motor runs in the opposite direction to the default direction
RUN A/B	The effective level is based on the COM port status/specific functions.
сом	Please connect 0V when inputting and outputting PNP signal; Please connect 24V when inputting and outputting NPN signals.
485A/B 485 communication interface	

# **Run A and Run B**

Run A	Run B	Describe
ON	OFF	Drum motor runs at 100% fixed set speed
ON	ON	Drum motor runs at 75% fixed set speed
OFF	ON	Drum motor runs at 50% fixed set speed
OFF	OFF	Drum motor stops running

model	VECTOR-T100
Rated power input	24V/48V
Allowable voltage range	20~28/40~60V
Allow voltage fluctuations	±15%
Driver peak input current	5A

#### Notice:

1. The green light turns on when the motor receives the control signal;
2. The peak current in the above table is the DC bus current limit value of the controller. After reaching the limit current, it will maintain the limit current and continue to output. output.



#### **Motor Port**

Pin serial number	name	Remark
1	Hall sensor GND	GND
2	Hall sensor positive pole	Hall sensor positive pole
3	Coil U	Coil U
4	Coil V	Coil V
5	Coil W	Coil W
6	Hall sensor U	Hall sensor U
7	Hall sensor V	Hall sensor V
8	Hall sensor W	Hall sensor W
9	Temperature sensing line	/

Note: When the lead wire of the electric drum motor is connected to the controller end or the extension cord end, the connector needs to be plugged in tightly so that the white positioning line on the male head is completely covered by the female head (the white line on the female head is not exposed), and it is determined to be a connector. Insert firmly into place.



## **Power Supply Requirements**

Switching power supply selection requirements:

Electric drum power	Switching power supply power	
40w	60W~80W	
80w	120W~160W	
100w	150W~200W	



Do not allow any liquid to penetrate inside the controller, otherwise it may cause damage to the controller.

#### The power supply of the controller needs to meet the following requirements::

- $\blacksquare \ \, \text{The output current of the 24V/48V power supply needs to meet the current supply of 5A for each driver card.}$
- Has NEC Class II certification
- The power output has suitable short circuit and overload protection

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